Features



# HDUF/FB series component type

The HDUF/FB series component type has pursued flatness and thinness. It consists of four parts and operates using the same principle as the cup type series.

The flexspline of the pancake type is shaped like the flexspline of the cup type with a cut bottom and is structured to have an additional circular spline with the same number of teeth as the flexspline.

Fig. 1-1

### Features of HDUF/FB series

- Flat and thin shape
- Compact and simple design
- High positioning and rotational accuracies
- Coaxial input and output

# Structure of the HDUF/FB series component type







\* The reduction ratio indicates the value for the following condition. Input: wave generator, fixed: circular spline S, output: circular spline D

\*\* Model names: HDUF for European markets, FB for Asia and North America

# Rotational direction and reduction ratio





Technical Data

Rating	table	e	15	5													
$\Pi$			IRI	$R \sim 1$													Table 3-1
Model	Rec	duc- on	Rated torque at input 2000rpm		Permissible peak torque at start/stop		Permissible max. value of ave. load torque		Instantaneous permissible max. torque		Rated input rotational speed	Permiss input ro speed	ible max. otational (rpm)	Permiss input ro speed	ible ave. tational (rpm)	Ine mon	rtia nent
	rat	atio	Nm	kgfm	Nm	kgfm	Nm	kgfm	Nm	kgfm	rpm	Oil Iubricant	Grease Iubricant	Oil Iubricant	Grease Iubricant	l ×10⁻⁴kgm²	J ×10 <sup>-5</sup> kgfms²
14	5	0	2.6	0.27	3.2	0.33	3.2	0.33	6.9	0.7							
	8	8	4.9	0.5	7.8	0.8	7.8	0.8	15.7	1.6*	2000	6000 3600	4000 2500	0.033 0	0.034		
14	10	00	5.9	0.6	9.8	1.0	9.8	1.0	15.7	1.6*	2000	0000	0000 3000	4000	2000	0.033	0.004
	11	10	5.9	0.6	9.8	1.0	9.8	1.0	15.7	1.6*							
	5	0	14	1.4	18	1.8	18	1.8	34	3.5							
	8	0	17	1.7	21	2.1	21	2.1	35	3.6	2000	6000 3600					
20	10	00	22	2.2	26	2.7	25	2.5	47	4.8			3600	3600	2500	0.135	0.138
	12	28	24	2.4	33	3.4	25	2.5	58	5.9							
	16	60	24	2.4	38	3.9	25	2.5	59	6.0*							
	5	0	23	2.3	30	3.1	30	3.1	54	5.5	2000			3000	2500	0.36	0.37
	8	0	31	3.2	39	4.0	39	4.0	70	7.1		5000 3600					
25	10	00	39	4.0	52	5.3	52	5.3	91	9.3			3600				
	12	20	39	4.0	61	6.2	61	6.2	94	9.6*							
	16	60	39	4.0	76	7.8	61	6.2	86	8.8*							
	5	0	44	4.5	60	6.1	60	6.1	108	11	2000						
	7	8	63	6.4	75	7.7	75	7.7	127	13				2500	2300	1.29	1.32
32	10	00	82	8.4	98	10	98	10	176	18		4500	3600				
	13	31	82	8.4	137	14	118	12	235	24 *							
	15	57	82	8.4	157	16	118	12	235	24 *							
	5	0	88	9	118	12	118	12	216	22							
	8	0	118	12	147	15	147	15	265	27							
40	10	0C	157	16	186	19	186	19	343	35	2000	4000 3300	2000 2000	2000	3.38	3.45	
	12	28	167	17	235	24	235	24	372	38*							
	16	60	167	17	284	29	274	28	353	38 *							
	8	0	216	22	265	27	265	27	480	49				1700 1700		0.0	10
50	10	00	284	29	253	36	353	36	627	64	1700	3500	2500 2000		1700		
50 -	12	20	304	31	421	43	421	43	706	72*	1700	3500	3000		1700	9.9	10
	16	60	304	31	510	52	490	50	666	68 *							

\* The value of asterisk is limited by ratcheting torque.

(Note) 1. Inertia moment:  $I = \frac{1}{4}GD^2$ 





# **Measurement table**

								Unit: mn
Symbol		Model	14	20	25	32	40	50
φA(g7)			50	70	85	110	135	170
В			5	6	8	10	13	16
C	C*			0.5	0.5	0.5	1.0	1.0
D	)*		10.5	12.5	16.5	20.5	27	33
E	0 -0.1		15.0	11.4	12.8	15.6	19.4	23.2
Fr	*		3.75	0.95	0.35	0.95	1.8	2.9
Fa	F2*			2.05	3.35	3.95	5.8	6.9
φ	φG			60	75	100	120	150
Н			M3	M4	M5	M6	M8	M10
4		Standard	6	9	14	14	14	19
φ	л(н/)	Max. size	8	12	15	15	20	20
J	(Js9)		—	3	5	5	5	6
K	+0.1		—	10.4	16.3	16.3	16.3	21.8
φ	φL			20	26	26	32	32
φ	M		—	31.5	41	52	65	80
Х			C0.2	C0.2	C0.2	C0.2	C0.4	C0.4
Y			C1.0	C1.0	C1.5	C1.5	C2.0	C2.0
Z			—	R0.08~0.16	R0.16~0.25	R0.16~0.25	R0.16~0.25	R0.16~0.25
а			a 29		53	69	84	105
Mass (kgf)			0.1	0.3	0.5	1.0	1.8	2.9

(Note) For Circular spline D, the outer circumference is Size Y.

• The C, D and F1 and F2 sizes indicated by an asterisk are the mounting positions in the shaft direction and allowance of the three parts (wave generator, flexspline, circular spline) comprising HarmonicDrive<sup>®</sup>. Strictly observe these sizes as they affect the performance and intensity.

• Four parts (wave generator, flexspline, circular spline D, circular spline S) are not assembled when the product is delivered.

# Efficiency characteristics

Efficiency varies depending on the reduction ratio and is subject to the input rotational speed, load torque and oil temperature. It looks like graph 5-1 when the product is operated at 100% of the rated load in the catalog at  $40^{\circ}$ C.

(Note) The efficiency is increased by about 10% for the grease lubrication.

# Graph 5-1

# No-load running torque, starting torque, backdriving starting torqu

Graph 5-2 shows the result of measurement when the component has been built in as the double shaft-type reducer. The values include frictional resistance due to the oil seal of the input and output shaft, and oil bath-type lubrication.

- No-load running torque .....This is the torque on the high-speed shaft required for rotation in a no-load condition. The value in the graph indicates the condition when the input rotational speed is 1500 rpm and the oil temperature is about 40°C.
- 2. Starting torque ..... This is the static torque required to start the high-speed shaft in a no-load condition.
- 3.Backdriving starting torque.. This is the static torque required to start the low-speed shaft in a no-load condition.



# Lost motion and the spring constant

Lost motion and the spring constant of the pancake type is the value when the wave generator and one of the circular splines is fixed and when a torque is applied to the other circular spline.

	OP				Table 5-3		
$\left< \right>$	Model	Lost motic	on (arc min)	Spring constant (kgm/min)			
[]	No.	± Load (kgm)	Standard product	Load (kgm)	Spring constant		
/	14	0.04	41.0	0.8	0.05		
	20	0.12	40.0	2.5	0.35		
	25	0.23	37.0	4.0	0.50		
	32	0.46	35.0	10	1.2		
	40	0.92	33.0	16	2.1		
$\sum$	50	1.73	29.0	30	4.4		

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# Design guide

# Component Type HDUF/FB

# Installation precision

Maintain the recommended precision shown in figure 6-1 and table 6-2 to fully bring out the excellent performance of HarmonicDrive<sup>®</sup> for assembled design.

# Recommended precision for assembly



# Recommended precision for assembly

Mode 0.013 0.017 0.024 0.026 0.026 0.028 а b 0.015 0.016 0.016 0.017 0.019 0.024 0.016 0.020 0.029 0.031 0.034 С 0.031 0.013 0.017 0.024 0.026 0.026 0.028 d 0.015 0.016 0.016 0.017 0.019 0.024 e 0.016 0.020 0.029 0.031 0.031 0.034 f g 0.011 0.013 0.016 0.016 0.017 0.021 h 0.007 0.010 0.012 0.012 0.012 0.015

# Precautions on installation



Table 6-2 Unit: mm

Fig. 6-1

# Lubrication

There are two types of lubrication; oil lubrication and grease lubrication. Although oil lubrication is common, grease lubrication is applicable to intermittent operation.

# Oil lubrication

# 1. Types of lubricant

Mineral oil CLP 68 (ISO VG 68) according to DIN 51517 T3.

### 2. Oil quantity

The oil level shall be the position shown in Table 7-2. Take action to increase the oil quantity as less oil can deteriorate the oil earlier.

|--|

Fig. 7-1

Oil level position							
Model	14	20	25	32	40	50	
А	7	12	15	19	24	29	

### 3. Replacement of oil -

First time ...... 100 hours after starting operation Second time and after .... Every 1000 operation hours or every 6 months

Note that you should replace the oil earlier than specified if the operating condition is demanding.

## Grease Iubrication

Different from oil lubrication, as a cooling effect is not expected from grease lubrication, it is only available for short operation.

	Operating condition: ED%	10% or less, continuous operation for 10 minutes or
		less, the maximum permissible input rotational speed
		in Table 3-1 or less
•	Recommended grease:·····	Harmonic grease SK-1A for model numbers 20 to 100 Harmonic grease SK-2 for model number 14

(Note) If you use the product over ED% or the maximum permissible rotational speed, the grease will deteriorate, will not work as a lubricating mechanism and will result in damaging the reducer earlier. Extreme care should be taken.

Table 7-2

